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Model-Based Design - Driving Innovation in High-Precision Medical Endoscope Image Processing Algorithms

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MATLAB EXPO

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Current Limitations of Endoscope Systems

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5

Rapid Algorithm to FPGA Code Conversion Using MATLAB

1.1 Xishan Technology

Leading Domestic Brand for Surgical Power Devices

Chongqing Xishan Technology Co., Ltd. was established in December 1999, focusing on surgical instruments, especially minimally invasive surgical instruments. The company engages in the R&D, production, and sales of surgical power devices, endoscopes, and energy surgical equipment, primarily used in neurosurgery, ENT, orthopedics, breast surgery, and other clinical departments.

Main Products:

1. **Surgical Power Devices:** Used for cutting, grinding, sawing, milling, and trimming bone and soft tissue in surgeries.
2. **Endoscopes:** Including ENT scopes, arthroscopes, foraminal scopes, laparoscopes, etc.
3. **Energy Devices:** Ultrasonic bone knives, plasma surgical systems, high-frequency surgical systems used in general surgery, ENT, orthopedics, etc.

Number of employees: 619

Key Achievements:

National High-Tech Enterprise

National Intellectual Property Demonstration Enterprise

National Specialized and New “Little Giant” Enterprise

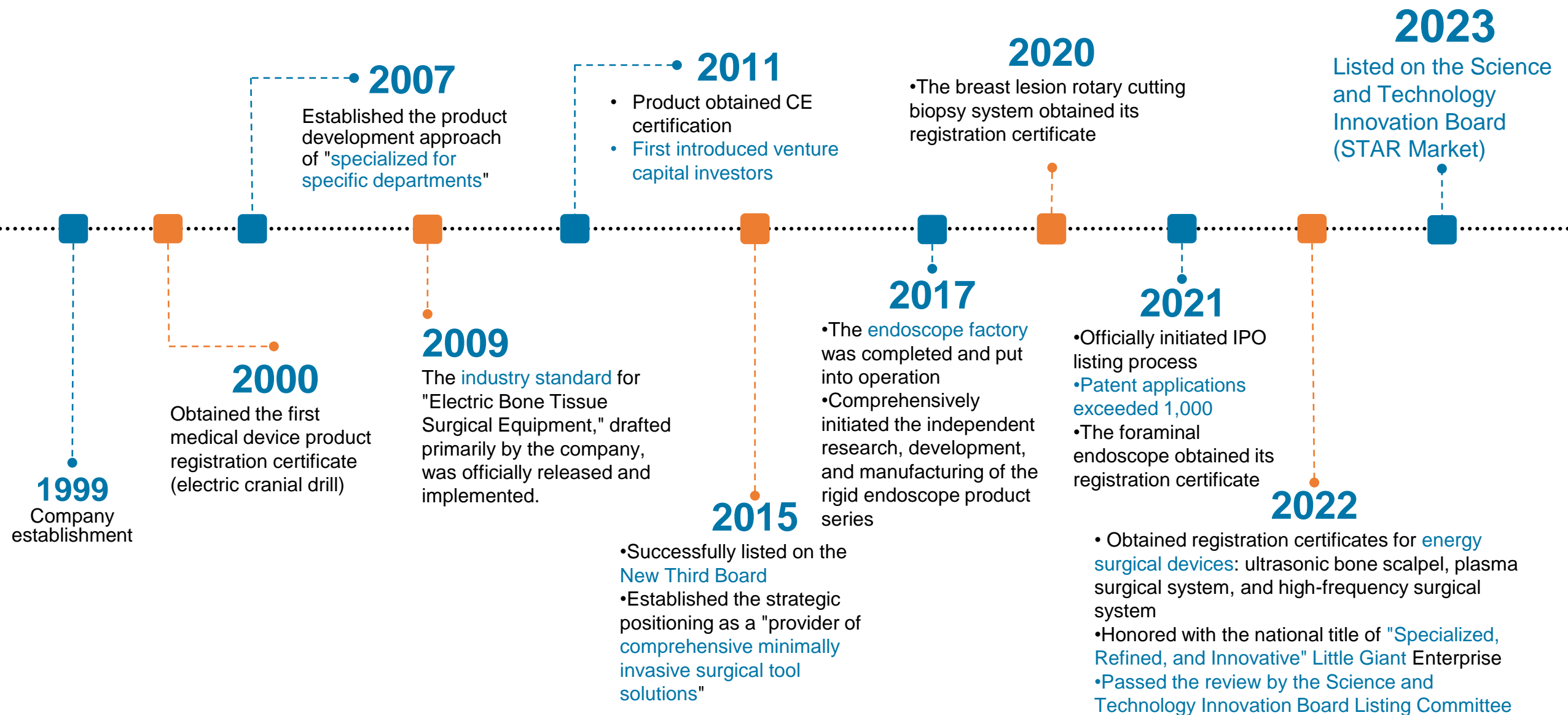
Licensed for Class II and III medical device production

Mission and Vision:

- **Purpose:** Contribute to human health
- **Mission:** Empower doctors, assist patients in recovery
- **Strategic Positioning:** Provider of comprehensive solutions for minimally invasive surgical tools
- **Strategic Goals:** Become a world-class minimally invasive medical device technology company and a representative enterprise of Chinese medical devices



1.2 Company History



1.3 Endoscope Products



Endoscope imaging system
(Registration No. Yuxie Zhun 20212060140)

Sinuscope



Registration No.
20202060078

Otoscope



Registration No.
20202060080

Laryngoscope



Registration No.
20202060079

Arthroscope and accessories



Registration No.
20203060910

Foraminal endoscope



Registration No.
20212060246

Laparoscope



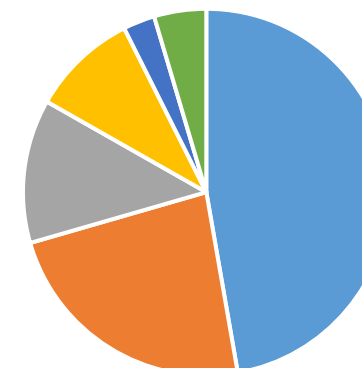
Registration No.
2022060331

Hysteroscope



Registration No.
20232180476

Endoscope Market Landscape



- Karl Storz
- Olympus
- Stryker
- Richard Wolf
- Shenyang Shenda
- Others

Market Space:

The total value of the Chinese rigid endoscope market is approximately 8 billion RMB. Karl Storz holds about 47% of the market share, Olympus holds about 23%, and domestic companies hold less than 10%. The low level of import substitution reflects the high entry barriers in the industry.

Development Goals:

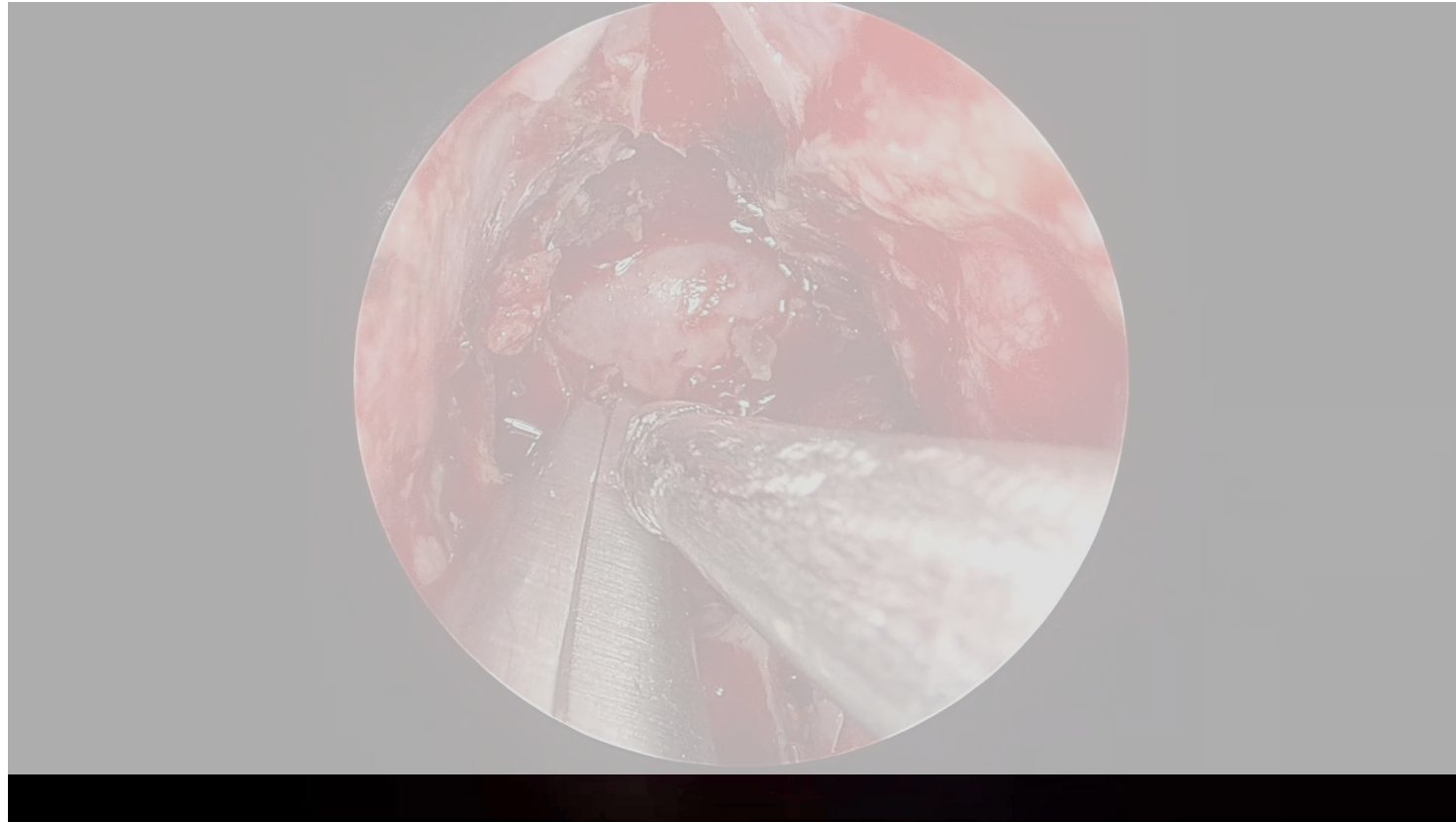
Position as a world-class company.

Product Highlights:

Self-developed lens optical materials and coating technology.

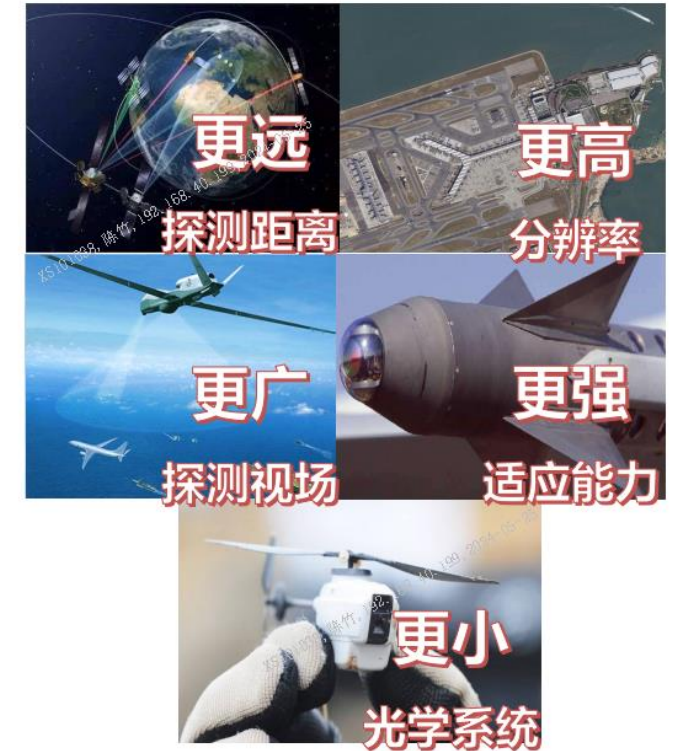
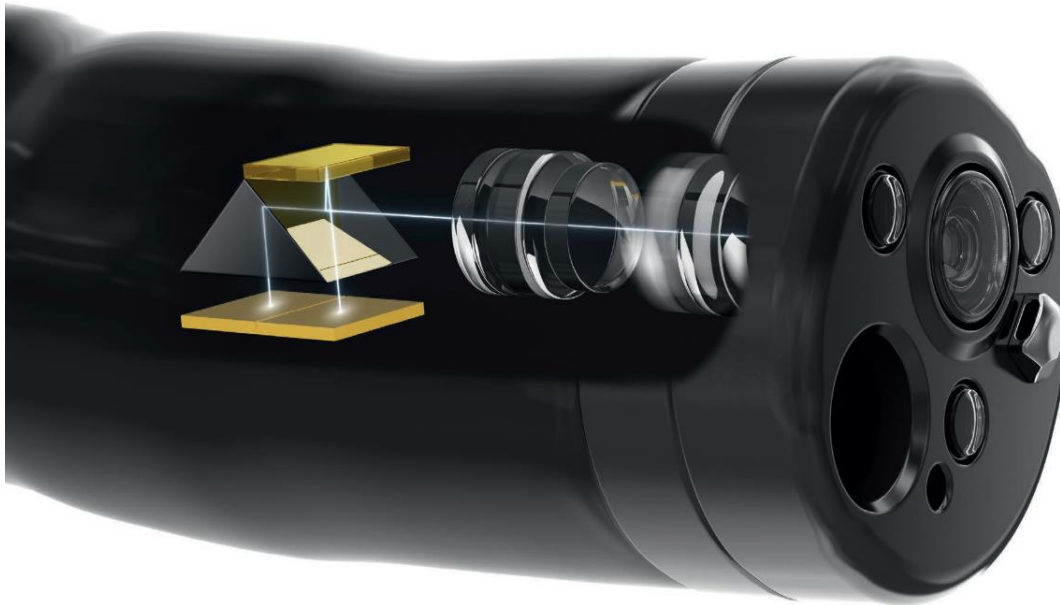
Note: Endoscope market data is sourced from "China Medical Devices" and Frost & Sullivan.

2. Surgical Scenarios



3. Current Limitations of Endoscope Systems

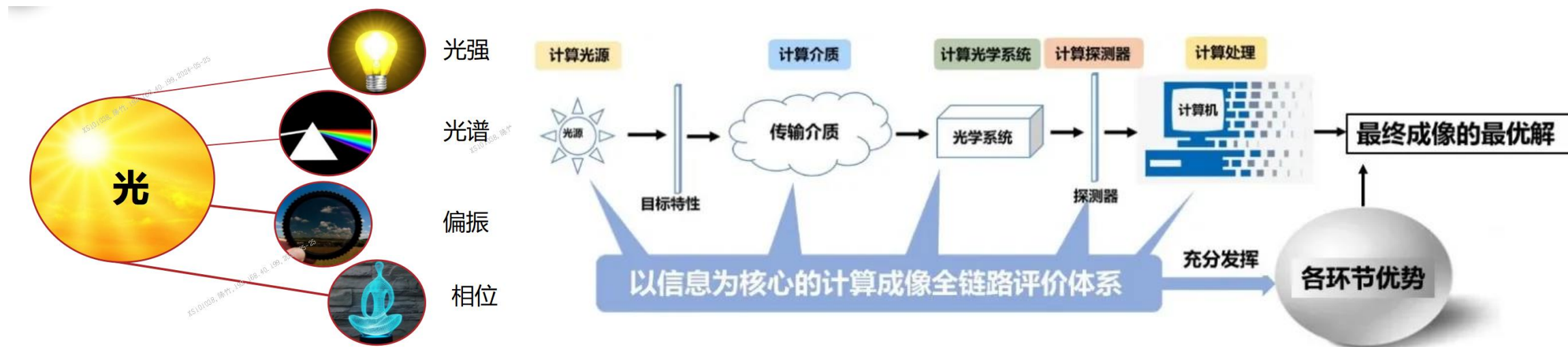
The limitations of traditional optical systems:
can't see, can't see clearly, can't see far, large size.



Aiming to quickly overcome these limitations and support clinical applications through a dual drive approach of "MATLAB" and "computational imaging"!

4.1 Introduction to Computational Imaging Technology

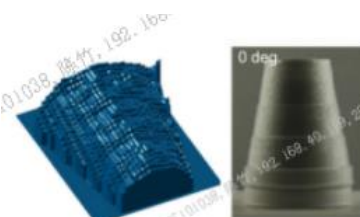
Computational imaging technology combines optics, sensor technology, computational algorithms, and system design. By incorporating computational processing during the imaging process, it surpasses the performance limitations of traditional imaging systems. The core idea of this technology is to introduce information processing at the image capture stage, thereby improving image quality, enhancing imaging functions, or reducing hardware complexity.




By acquiring more light field information, it enables higher-dimensional imaging.

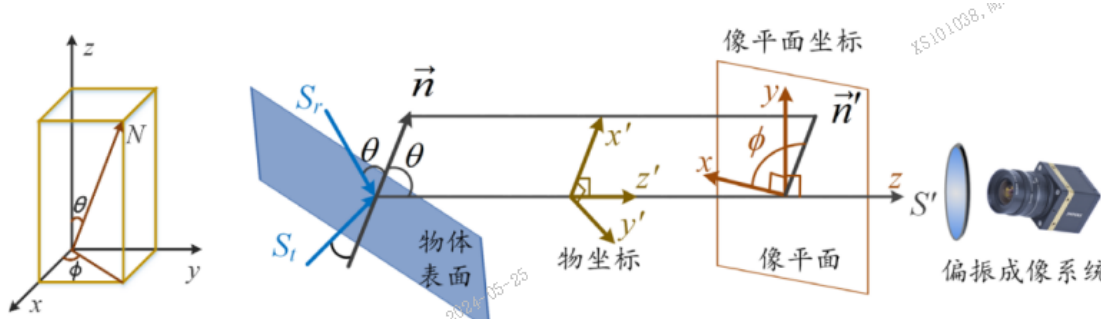
4.1 Introduction to Computational Imaging Technology

A Polarization Camera Can Also Achieve 3D Reconstruction



偏振三维成像结果






物体表面法向量模型

$$\vec{n} = \begin{bmatrix} n_x \\ n_y \\ n_z \end{bmatrix} = \begin{bmatrix} \cos \theta \cos \varphi \\ \cos \theta \sin \varphi \\ \sin \theta \end{bmatrix} = \begin{bmatrix} \tan \theta \cos \varphi \\ \tan \theta \sin \varphi \\ 1 \end{bmatrix}$$

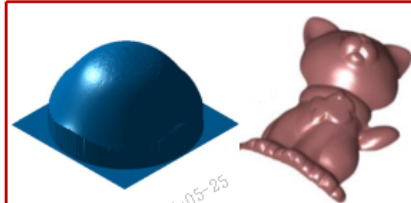
系统结构简单

表面纹理信息
成像精度高

性价比高



一个最简单的偏振成像系统



偏振三维成像结果示例

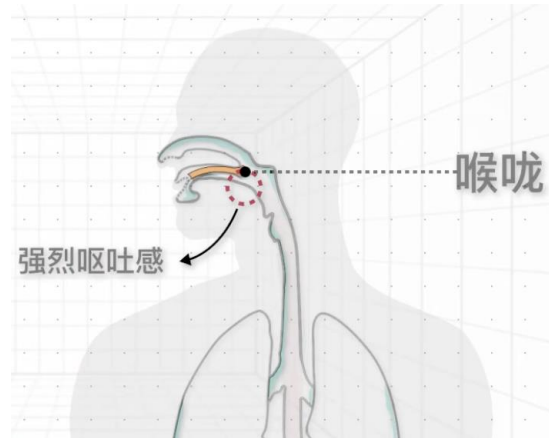
偏振信息解译

$$P = \frac{\left(n - \frac{1}{n}\right)^2 \sin^2 \theta}{2 + 2n^2 - \left(n - \frac{1}{n}\right)^2 \sin^2 \theta + 4\cos\theta\sqrt{n^2 - \sin^2\theta}}$$

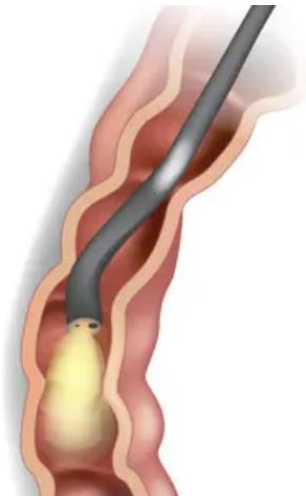
$$I(\phi_{pol}) = \frac{I_{\max} + I_{\min}}{2} + \frac{I_{\max} - I_{\min}}{2} \cos(2(\phi_{pol} - \varphi))$$

Note: Content source - School of Optoelectronic Engineering, Xidian University.

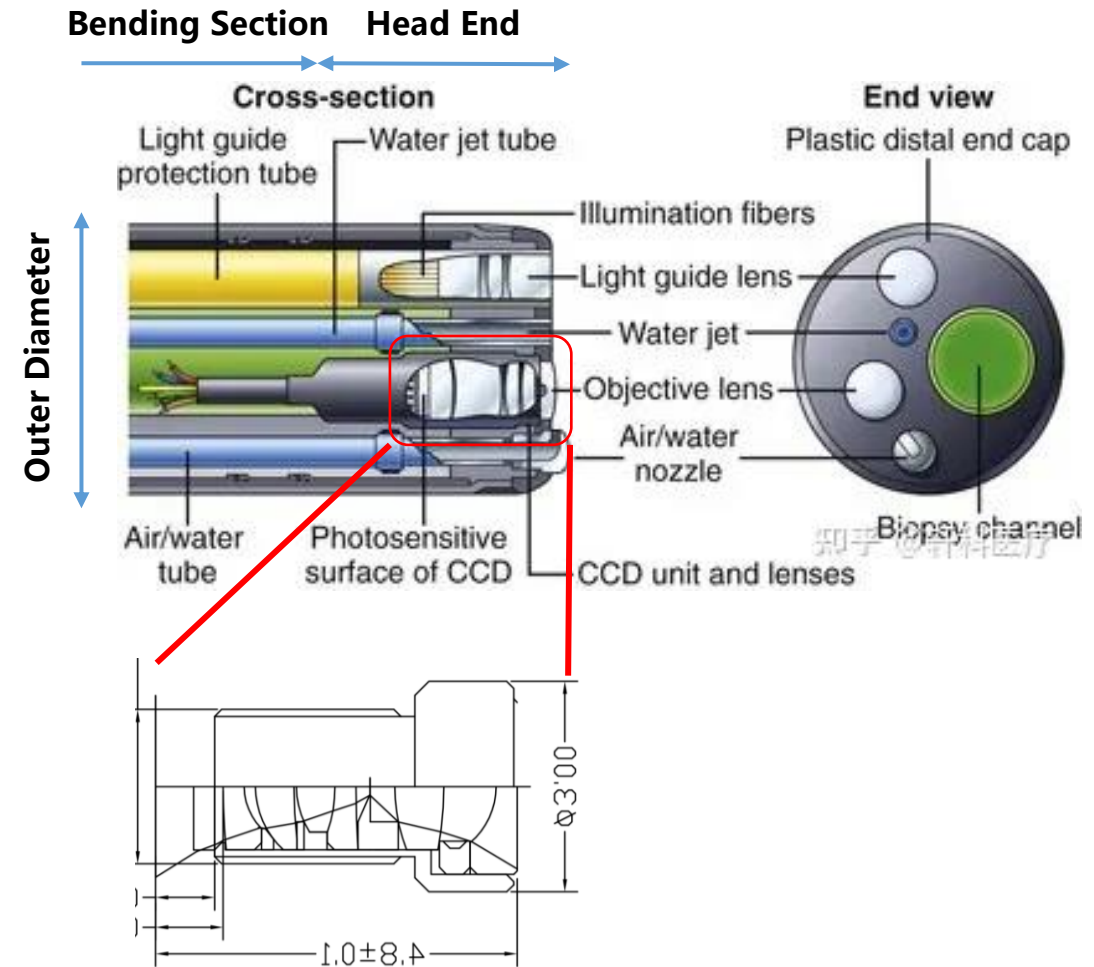
4.2 Limitations of Endoscope Systems - Space Constraints



**Thin
Outer
Diameter**



**Short
Head
End**

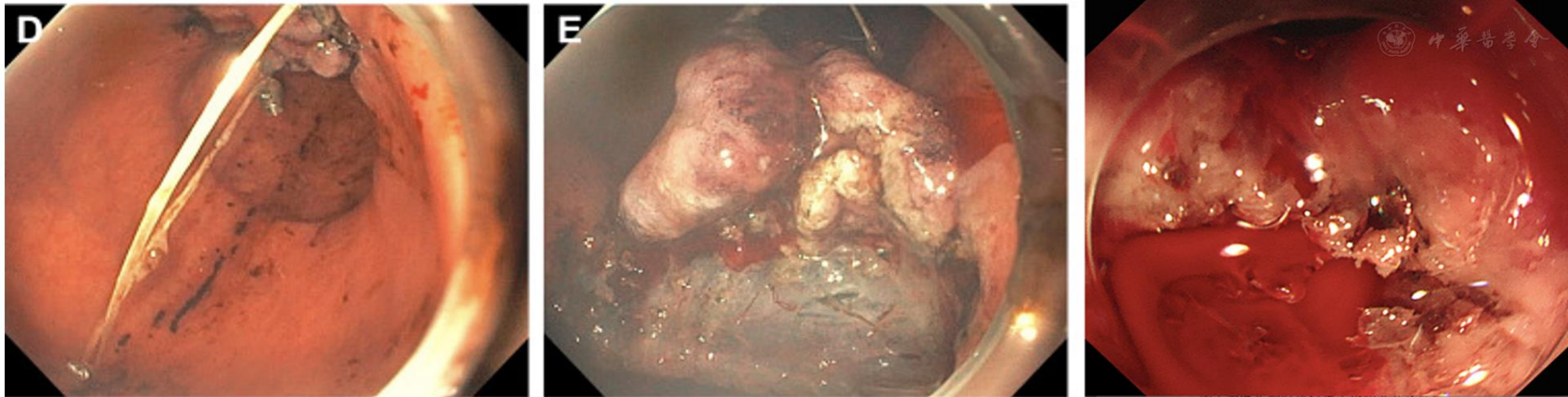


Dancing in shackles within limited space

4.3 Limitations of Endoscope Systems - Environmental Constraints

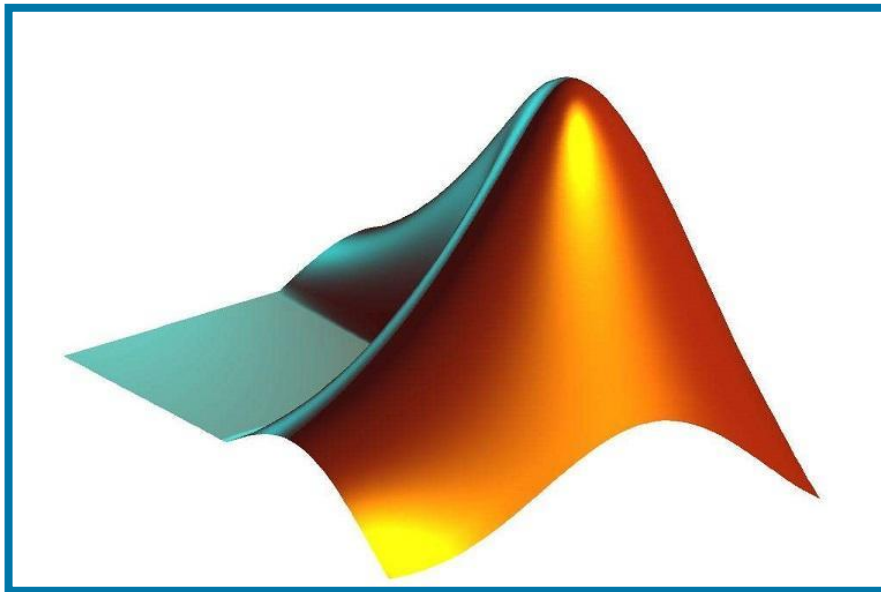
The natural body cavities are high-humidity environments filled with mucus and prone to bleeding.

During endoscopic examinations, the endoscope's head end is constantly moving, making it easy for mucus, smoke, and blood to contaminate the field of view.



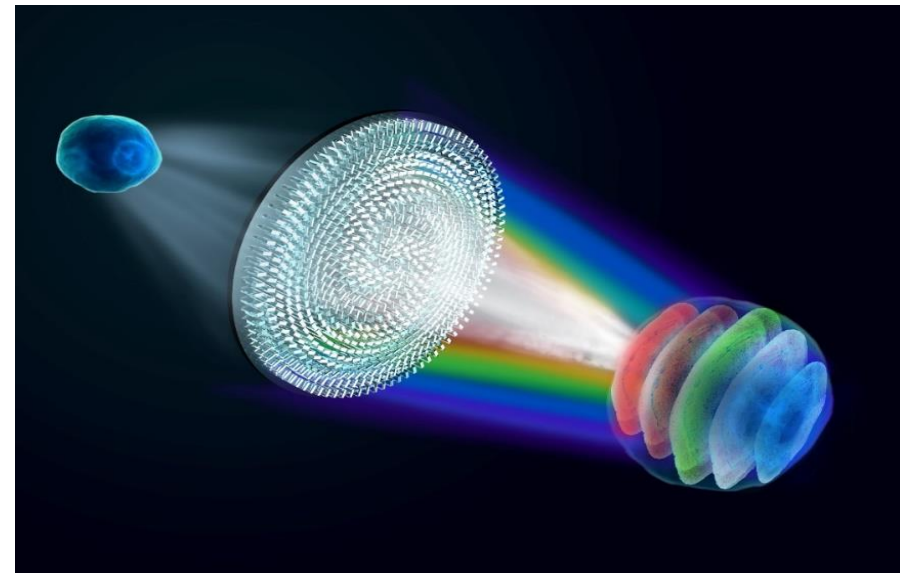
4. Dual-Drive Approach to Overcome Endoscope System Limitations

Rapid algorithm deployment to FPGA



MATLAB

Enhances image quality and functionality
beyond traditional imaging systems



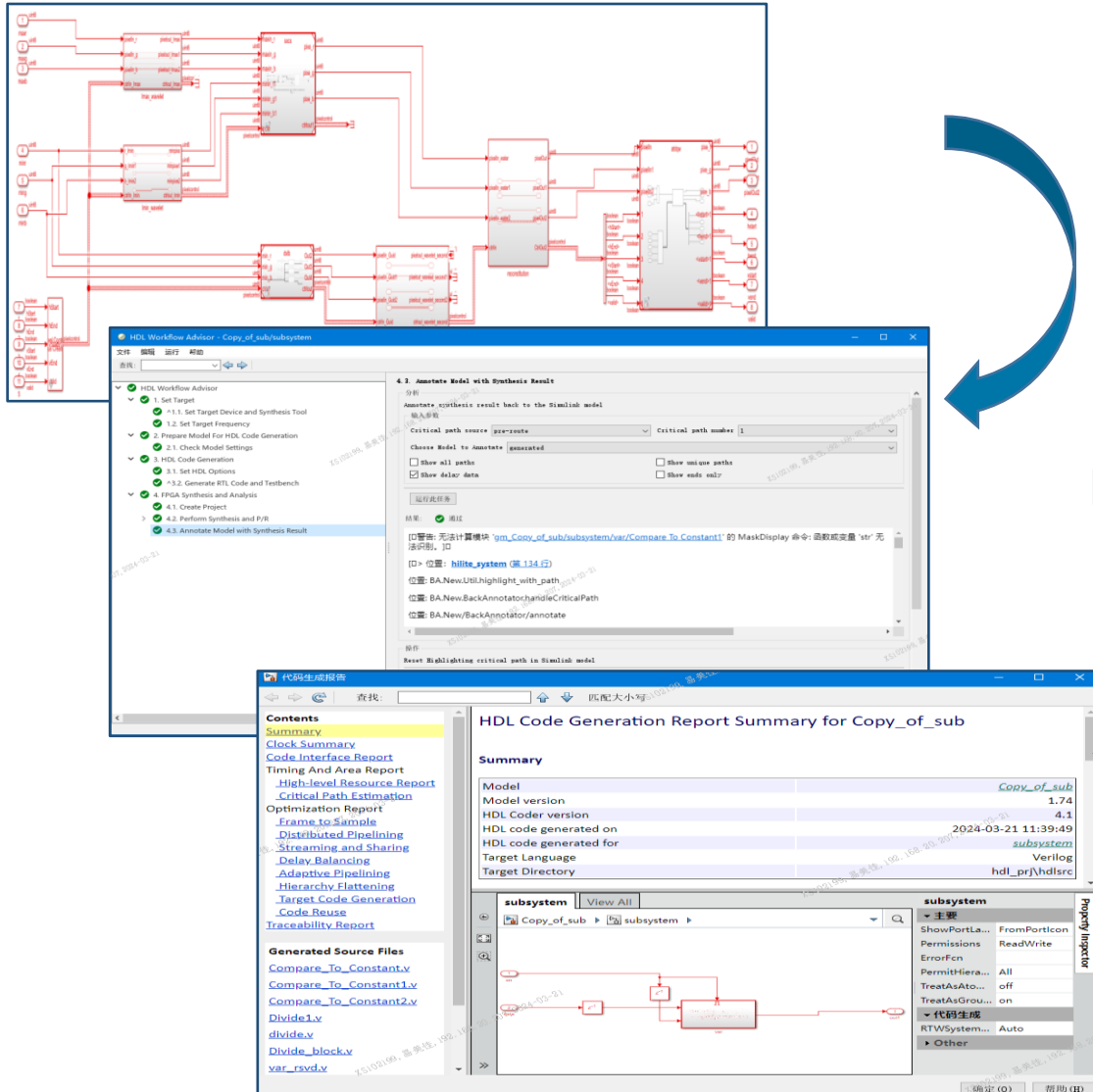
Computational Imaging Technology

Dual Drive

5.1 Challenges in Implementing High-Performance Medical Image Processing Algorithms on FPGA

- Algorithm development cycles are long, and experimental scenarios/data are often insufficient.
- The complexity of hardware and software environments makes real-time evaluation of algorithm performance and resources difficult.
- Algorithms need to be handed over to the FPGA team for implementation, requiring scheduling and planning.
- There are multiple ways to implement the same algorithm, making it impractical for the FPGA team to implement all versions.
- Significant differences exist between algorithm simulation results and FPGA implementation effects, necessitating rapid prototyping for comparison.
- HDL code simulation is slow, and design modification cycles are long, requiring higher abstraction levels to speed up iteration efficiency.
- Diverse and high-demand customization requirements in the domestic market make it challenging to respond quickly.

5.2 Rapid Algorithm to FPGA Code Conversion Using MATLAB



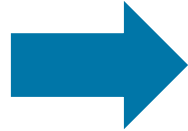
1. HDL Coder automatically generates standardized code.

2. Various resource and timing optimization strategies.

3. Generates comprehensive reports for traceability.

5.2 Rapid Algorithm to FPGA Code Conversion Using MATLAB

Computational
Imaging
Technology

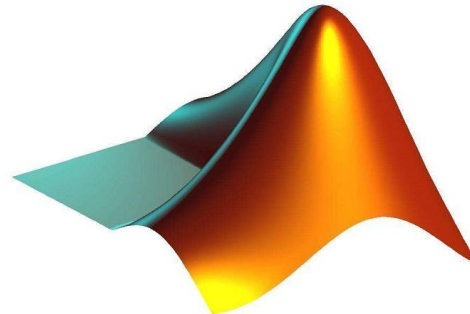


MATLAB Platform

1. MATLAB: Facilitates rapid iteration and validation of algorithm requirements.
2. Simulink: Quickly deploys algorithm models based on hardware architecture.
3. HDL Coder: Automatically generates code with high standardization, execution efficiency, maintainability, and portability.



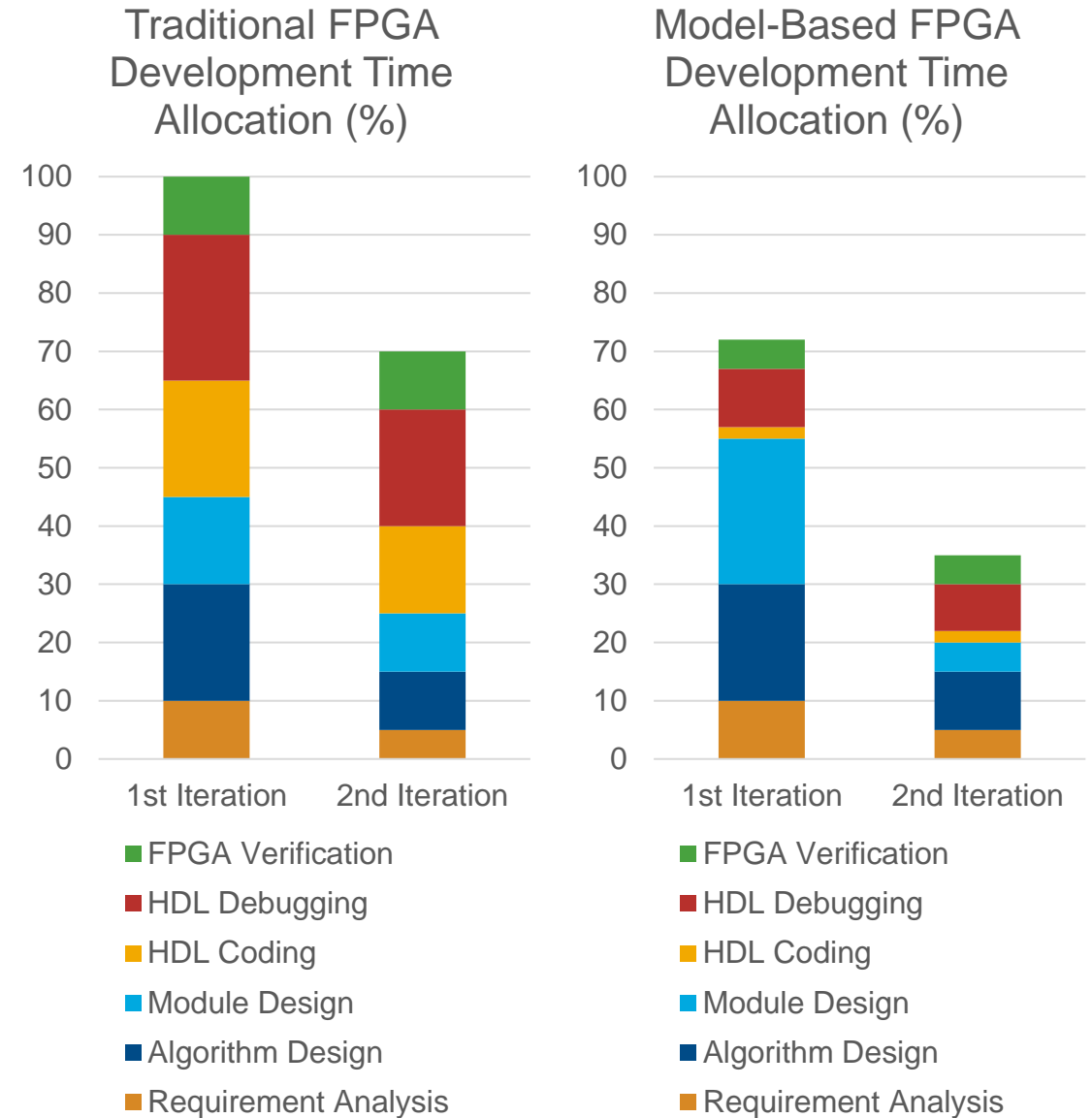
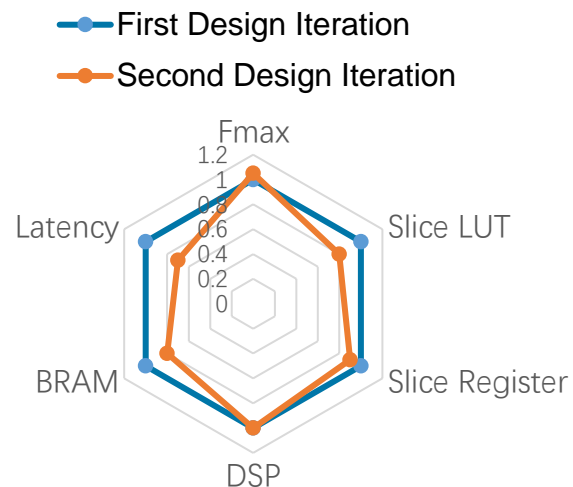
Rapid Algorithm
Deployment to FPGA



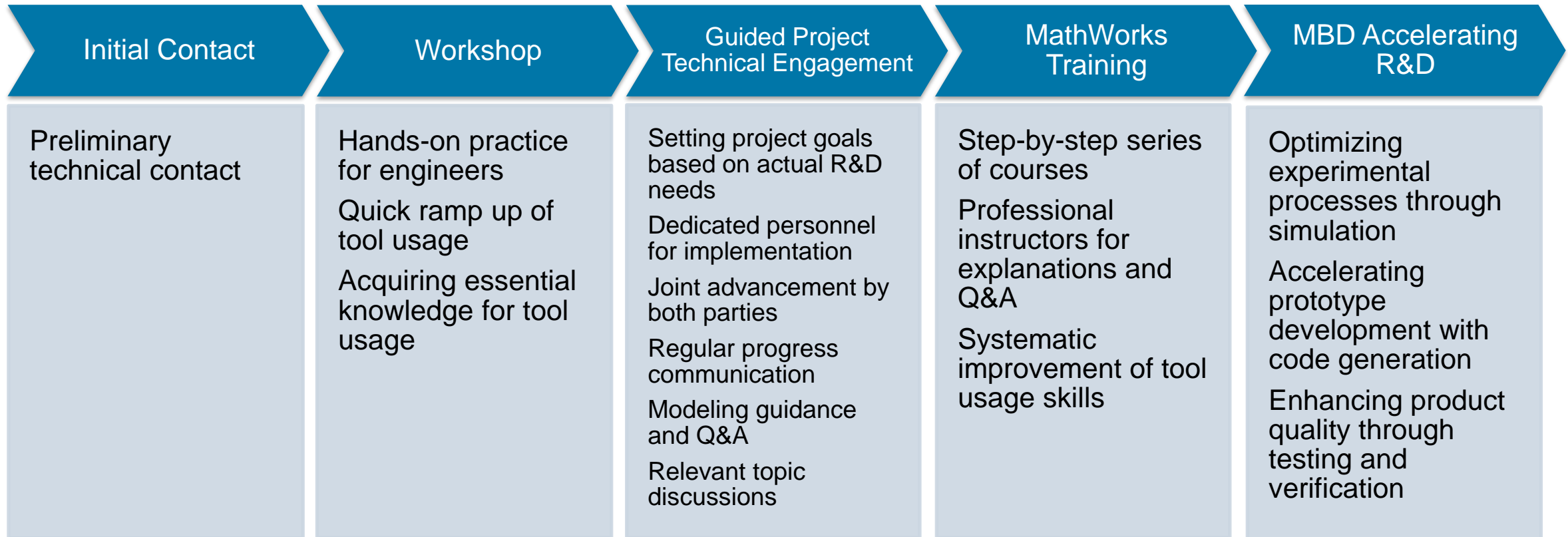
5.3 Advantages of Model-Based FPGA Algorithm Development

- Accelerate Design Iteration and Improve Development Efficiency.
- Models are easier to modify, allowing for quick implementation of design changes.
- The generated code is highly readable and easy to integrate.
- Facilitates design reuse through modular development.
- Ensures that all performance metrics are balanced and meet expectations after implementation.

Comparison of Two Design Iterations



Collaboration Between Xishan Technology and MathWorks



MATLAB EXPO

Thank you



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