

Weapon System Fault Detection, Isolation, and Analysis using Stateflow[®]

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- The challenge
- Types of faults
- Fault detection, isolation, and analysis
- Benefits of Stateflow[®]



System Overview

- Non-Line of Sight Cannon (NLOS Cannon) Concept Technology Demonstrator (CTD)
 - Proof-of-principle test-bed
 - Drawing board to fully operational demonstrator in 7 months

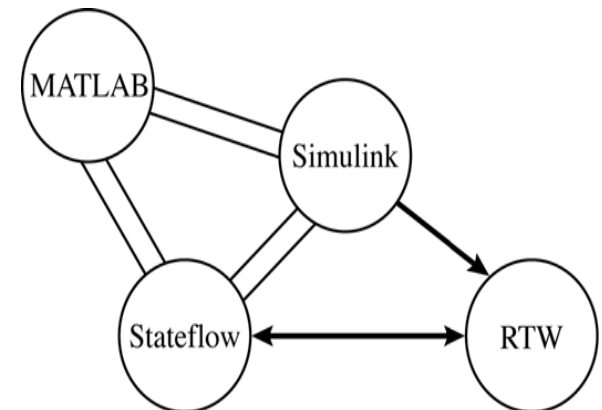
- NLOS Cannon is part of the Future Combat Systems (FCS) family of Manned Ground Vehicles (MGV)
 - Begin initial production by 2008 with initial NLOS Cannon fielding by 2012
 - 27-ton, large-caliber, self-propelled cannon system with automated ammunition handling

The Challenge

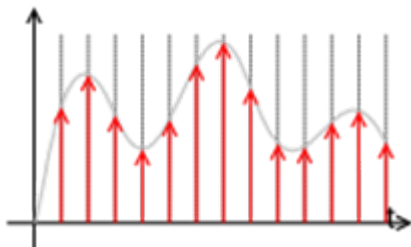
- Maximize code reuse while supporting the following additional requirements
 - Propellant carried on vehicle increased by 10%
 - Firing rate increased by 66%
 - Support Multi Round Simultaneous Impact (MRSI) capability
 - Redesign propellant handling system
 - Support next-generation of servo motor controllers



- MATLAB[®] and Simulink[®]
 - Modeling of algorithmic behavior, control system development and analysis
 - Model-Based Design, plant models
- Stateflow
 - Modeling of logic behavior
 - Fault detection, isolation and analysis
- Real-Time Workshop
 - Automatic code generation
 - Hardware in the loop integration and test
 - Requirements development
 - Document design



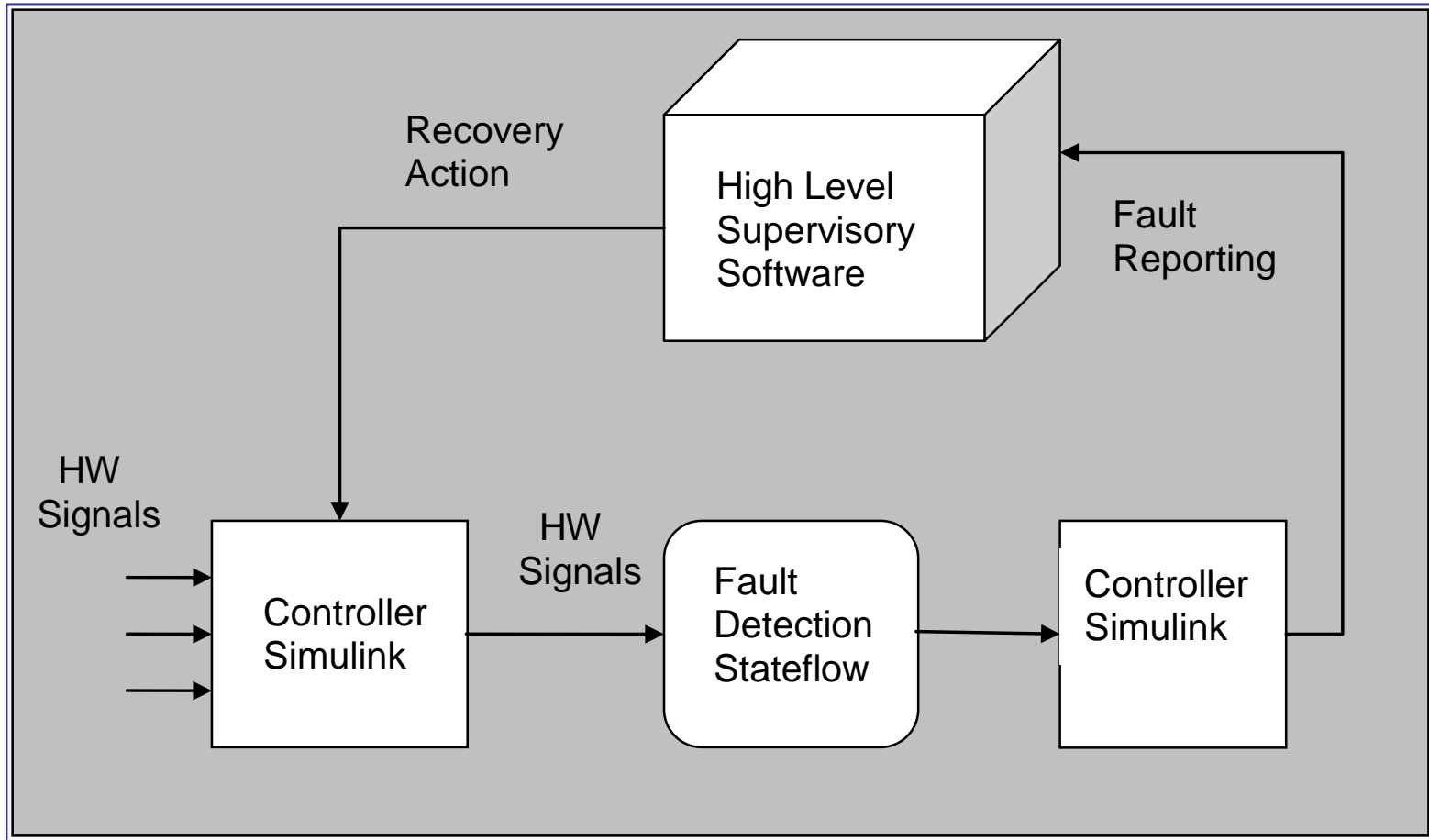
- Analog Signals
 - Monitoring for out of range condition, higher or lower than a predetermined threshold
- Resolver Signals
 - Monitoring for correct alignment, stroke length, move completion, and position errors
- Discrete Signals
 - Monitoring health of subsystems and electronics, including interlocks, switches, and other discrete feedback



- Sensor signals
 - Hardware -> Simulink -> Stateflow
- Sensor signals monitored continuously for satisfactory conditions
- Using parallel state charts, each fault condition is checked every sample time
- Sensor faults are monitored and reported independently

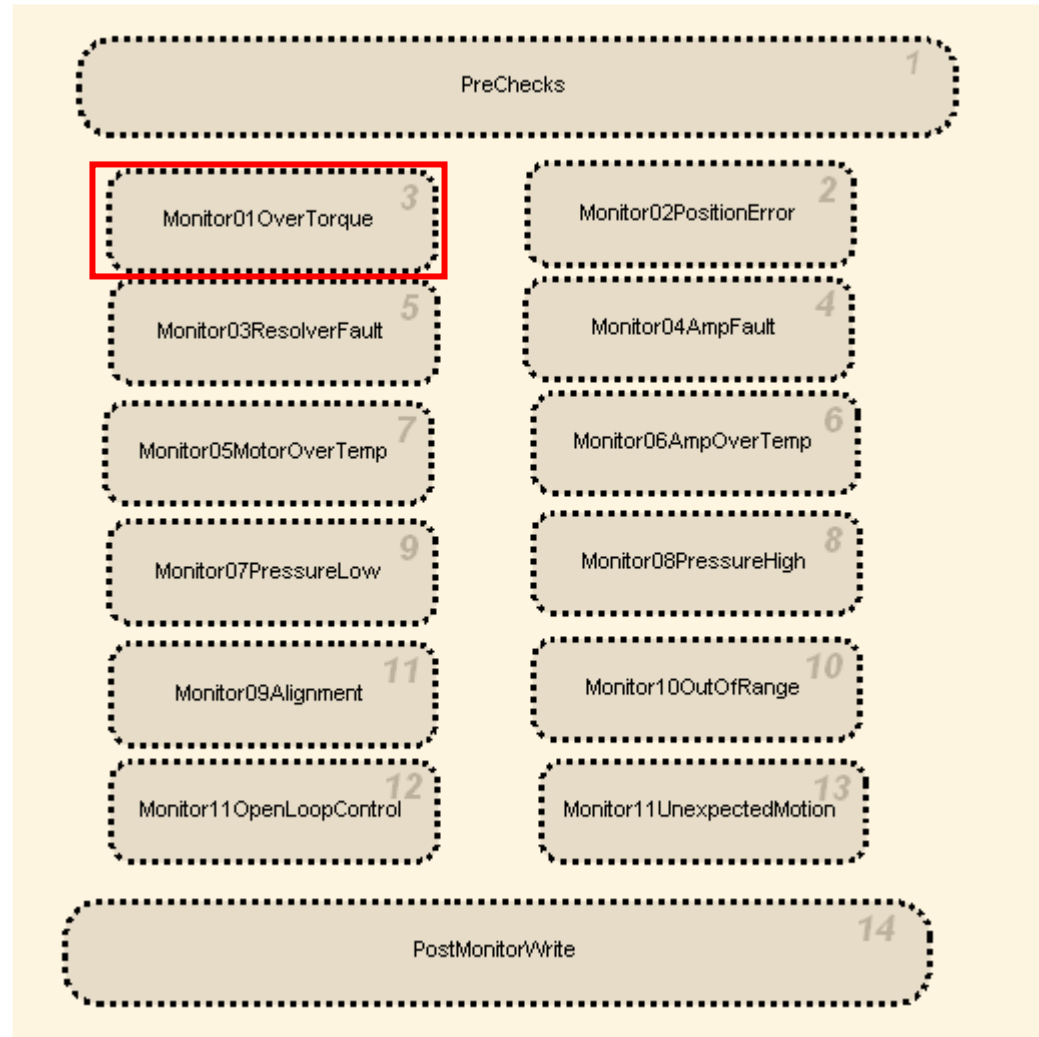


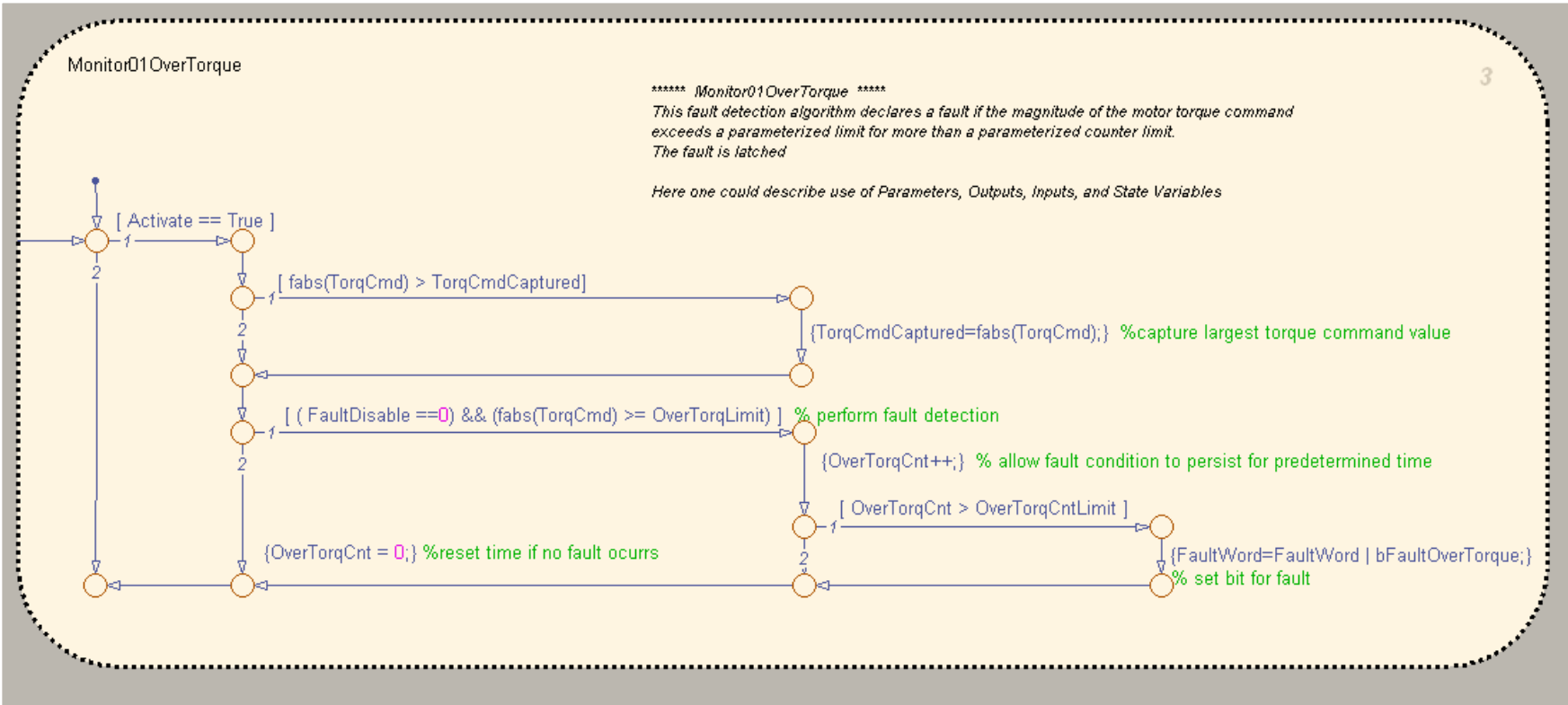
Fault Detection Overview



Fault Detection

- Fault monitors labeled and organized
- Faults isolated





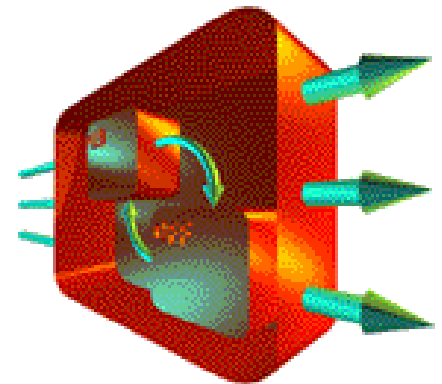
- Faults can be triggered with timing constraints specific to the sensor or measurement
 - i.e. Allow analog signal A to be out of range for no more than 20 ms while signal B can be out of range for 2 ms

- Failure modes can be constructed using complex logic on multiple signals
 - i.e. (Analog Signal A > Predetermined threshold) AND (Discrete Signal B == 1)

- Pre-check logic can set and reset flags that will skip specific faults according to user settings or current conditions in system
 - i.e. Check for fault condition only if fault check is not disabled
 - i.e. Check only if drive is active and aligned

- Faults are reported to higher level controller for isolation and further analysis
 - Each sensor checked for fault
 - Controller determines failure mode i.e. collision, improper use, working device outside of limits, electronics problems
 - Controller determines course of action i.e. E-Stop or warning
 - Fault is isolated and relayed to GUI for user action
 - Fault stays triggered until explicitly reset by controller
- Ability to log events for later playback and diagnosis off-line

- User receives notification of fault through higher level supervisory software, decides course of action i.e. fault reset
- Reset logic is fed back through the controller to Simulink, then to the fault monitor in Stateflow
- The fault reset signal goes into the fault monitor which clears the fault



- Fault monitor Stateflow chart can be saved in a library, allowing for code reuse

- Graphical representation helps to locate faults and bugs faster
 - Fault detection states are organized and easy to find
 - The logic transitions allow others besides the programmer to understand and debug code

- Comparison to hand code
 - Stateflow provides a natural graphical environment for complex logic transitions
 - Flow charts and parallel states are easier to implement, understand and maintain
 - Animation of transitions allows user to verify detection logic during development

- Seamless integration with...
 - MATLAB and Simulink
 - Systems Integration software and hardware
 - Data acquisition hardware (analog and digital)
 - Graphical User Interface development software
 - Hardware and software used for rapid prototyping and hardware in the loop simulations

- Decrease in software development time of 80%

- Stateflow and Real-Time Workshop suite can be used to
 - Develop requirements
 - Document design
 - Support testing
 - Automatically generate portable C code

Q and A